

NON-PROVISIONAL APPLICATION FOR UNITED STATES PATENT

FOR

**PERSISTENT NAMING FOR SUB-PATHS OF INTERMITTENT
FILLET WELD BEADS**

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PERSISTENT NAMING FOR SUB-PATHS OF INTERMITTENT FILLET WELD BEADS

BACKGROUND

Advances in computing technology have made possible the provision of
5 computer-aided-design (CAD) software to support the design and manufacturing of
articles. Modern CAD software not only includes sketching or schematic features,
but also solid modeling and other advanced features.

Manufacturing of articles often involves the welding of two or more
components of an article into one single piece. A variety of welding types may be
10 employed, including but not limited to intermittent fillet welds. Accordingly, it is
desirable for CAD software to support modeling of welds, in particular, intermittent
fillet welds. A modeled weld is often refers to as a weld bead. In the modeling of
intermittent fillet weld, it is important that the topological entities are uniquely named,
and these names are persistent across re-computations of the models, due to
15 topological changes resulting from e.g. user edits, modifying the weld bead
parameters, such as the number of weld bead instances. The requirements of
persistent names are that they should be unique and invariant under topology
changes.

A few commercial CAD systems offer support for representing welds.
20 Externally, the support includes highlighting and/or labeling of the edges of the
components involved. However, the method in which this functionality is provided is
proprietary, and not known. In particular, it is unknown how the topological entities
of an intermittent fillet weld bead are named.

BRIEF DESCRIPTION OF THE DRAWINGS

Embodiments of the present invention will be described referencing the accompanying drawings in which like references denote similar elements, and in which:

5 **Figure 1** illustrates a computing environment incorporated with one embodiment of the present invention;

Figures 2a-2b illustrate two examples of computing environments of **Fig. 1**;

Figure 3 illustrates an example machine readable article having instructions implementing all or portions of the CAD application of **Fig. 1**;

10 **Figure 4** illustrates one embodiment of the operational flow of the weld bead modeling function of **Fig. 1** for generating an intermittent fillet weld bead;

Figure 5 illustrates one embodiment each for the sub-path generating and naming operations of **Fig. 4** in further details;

Figure 6 illustrates the invariant weld generation direction establishment operation of **Fig. 5** in further details, in accordance with one embodiment;

15 **Figures 7a-7b** illustrates the persistent edge and vertex naming operations of **Fig. 5** in further details, in accordance with a respective embodiment;

Figures 8a-8c illustrate three examples of Global Start Vertex (GS) and Global End Vertex (GE) of **Fig. 6**;

20 **Figures 9a-9b** illustrate an example of a path being divided into sub-paths;

Figures 10a-10b illustrate an example naming of the path and the sub-paths, including their edges and vertices;

Figure 11 illustrates a situation where after sub-division, a vertex remains a member of two edges;

Figures 12a-12b illustrate two sub-path views of an example of persistent naming, across re-computations of an intermittent fillet weld bead model due to e.g. editing of the weld;

Figures 13a-13e illustrate an example triangular sweeping profile employed
5 to generate an intermittent fillet weld bead having multiple weld bead instances; and various resulting weld beads; and

Figures 14a-14b illustrate two external views of two other examples of persistent naming, across re-computations of two intermittent fillet weld bead models, due to direct editing of the weld beads.

DETAILED DESCRIPTION OF EMBODIMENTS OF THE INVENTION

Embodiments of the present invention include, but are not limited to, methods to name sub-paths, including their edges and vertices, of an intermittent fillet weld bead in a computing environment, instructions implementing or contributing to the
5 implementation of the methods, components, devices and systems incorporated with one or more implementations.

In the following description, various aspects of embodiments of the present invention will be described. However, it will be apparent to those skilled in the art that embodiments of the present invention may be practiced with only some or all
10 aspects described. For purposes of explanation, specific numbers, materials and configurations are set forth in order to provide a thorough understanding of these embodiments of the present invention. However, it will be apparent to one skilled in the art that various embodiments of the present invention may be practiced without the specific details. In other instances, well-known features are omitted or simplified
15 in order not to obscure the disclosed embodiments of the present invention.

Various operations will be described as multiple discrete operations in turn, in a manner that is helpful in understanding these embodiments of the present invention, however, the order of description should not be construed as to imply that these operations are necessarily order dependent. In particular, these operations
20 need not be performed in the order of presentation.

The phrase "in one embodiment" is used repeatedly. The phrase generally does not refer to the same embodiment, however, it may. The terms "comprising", "having" and "including" are synonymous, unless the context dictates otherwise.

Referring now to **Figure 1** wherein a computing environment incorporated
25 with one embodiment of the present invention is illustrated. As shown, for the

embodiment, computing environment **100** includes CAD application **112**, having associated user interface **102** and data representations **122**. CAD application **112** includes a number of CAD functions, in particular, weld bead modeling function **114** and shape manager **116**. The various CAD functions, including weld bead modeling function **114** and shape manager **116** are equipped to create, process and delete various data representations **122** of features of articles of manufacture, including in particular, data representations **126** of their components and edges, and data representations **128** of weld beads. Resultantly, articles of manufactures may be modeled **124**, and displayed **104** in user interface **102**, including their components, edges and weld beads, **106** and **108**.

Except for weld bead modeling function **114**, CAD application **112** including shape manager **116** represent a broad range of these elements, and may be implemented in a number of manners. For example, CAD application **112** may be implemented using the Inventor® 7 (also referred to as Autodesk Inventor Series) mechanical design software product available from Autodesk Inc. of San Rafael, CA.

In alternate embodiments, CAD application **112** including shape manager **116** may be implemented with other CAD applications with integral geometric modeler, or other CAD applications employing a complementary standalone geometric modeler.

Similarly, data representations **122** may be implemented in a variety of manners, including but are not limited to link lists, relational tables, data objects, and other data organizations/structures of the like. Likewise, user interface **102** may be implemented in any one of a number of manners, in particular, a graphical manner.

Figure 2a illustrates one embodiment of computing environment **100** of **Fig. 1**. As illustrated, for the embodiment, computing environment **100** is a computing device **200** incorporated with one embodiment of the present invention. More

specifically, computing device **200** includes processor **202**, memory **204**, mass storage device **206** and other I/O devices **208**, coupled to each other via bus **210**, as shown.

Memory **204** and mass storage device **206** include a transient working copy
5 and a persistent copy of CAD application **112**, including associated user interface **102** and data representations **122** of **Fig. 1**. Further, for the embodiment, memory **204** and mass storage device **206** include a transient working copy and a persistent copy of operating system **222**, providing a number of system services to CAD application **112**.

10 Processor **202**, memory **204**, mass storage **206**, I/O devices **208**, and bus **210** represent a broad range of such elements.

In other words, except for CAD application **112** endowed with weld bead modeling function **114**, computing device **200** represents a broad range of such devices, including but are not limited to a server, a desktop computer, a computing
15 tablet, a laptop computer, a palm sized personal assistant, a pocket PC, or other computing devices of the like.

Figure 2b illustrates another embodiment of computing environment **100** of **Fig. 1**. As illustrated, for the embodiment, computing environment **100** is a networked computing environment **250** including client device **252** and server **256**
20 coupled to each other via network **254**.

Collectively, client device **252** and server **256** are equipped with an embodiment of CAD application **112**, including associated user interface **102** and data representations **122**. In other words, CAD application **112**, including associated user interface **102** and data representations **122** are distributively disposed on client

device **252** and server **256**. In various embodiments, client device **252** and server **256** may be computing device **200** of **Fig. 2a**.

Similarly, network **254** represents a broad range of local area, wide area, private and/or public networks. An example of a public network is the Internet.

5 **Figure 3** illustrates a machine readable article suitable for use to store executable instructions implementing all or portions of the CAD application **112** of **Fig.1**, including weld bead modeling function **114**, in accordance with one embodiment. For the embodiment, the machine readable article includes storage medium **300** and instructions implementing all or portions of CAD application **112**,
10 including weld bead modeling function **114**, stored therein. The stored instructions may be used to program an apparatus, such as computing device **200** of **Fig. 2a**, or client device **252** and/or server **254** of **Fig. 2b**.

In various embodiments, the instructions may be C or C++ programming language instructions or other system programming language instructions of the like.
15 Further, storage medium **300** may be a diskette, a tape, a compact disk (CD), a digital versatile disk (DVD), a solid state storage devices, or other electrical, magnetic and/or optical storage devices of the like.

Figure 4 illustrates one embodiment of the operational flow of weld bead modeling function **114** of **Fig. 1**. The embodiment assumes CAD application **112**
20 includes the functions for facilitating entry into a weld modeling mode of operation, where on entry, weld bead modeling function **114** is invoked. Further, CAD application **112** includes the functions for facilitating selection of the edges and/or faces (FS1, FS2) of the components of an article of manufacture involved in a particular welding operation (including e.g. the weld type and the weld parameters)
25 to weld the components of the article together during manufacturing. For example,

CAD application **112** may include support to facilitate a user in making the selection using a cursor control device, such as a mouse, trackball, a touch pad and so forth. The support may leverage user input device services provided e.g. by operating system **222**.

5 As illustrated, in block **402**, on or after selection, weld bead modeling function **114** first collects the user input for the intermittent fillet weld (hereinafter simply intermittent weld). In block **404**, weld bead modeling function **114** generates a blank B. In one implementation, blank B is the result of a unite operation performed using a shape manager call, of all the copies of the components along which the
10 intermittent weld will be generated. Then, in block **406**, weld bead modeling function **114** generates and names path P. In one implementation, path P is generated from the blank B by collecting all the edges that have FS1 and FS2 as adjacent faces. These edges are copied and united to produce a wire-body, i.e. path P, using shape manager calls. In other words, path, P is a single non-degenerate piece which is
15 continuous, un-branched and has no self-intersections.

 In blocks **408-410**, weld bead modeling function **114** divides path P into sub-paths, and names the sub-paths including their edges and vertices, to be described more fully below. The actual curve splitting to generate the sub-paths is done using a shape manager call.

20 Then, in block **412**, for each sub-path, weld bead modeling function **114** generates (using shape manager calls) and names a sweeping profile. In block **414**, for each sub-path, weld bead modeling function **114** generates and names a sweep tool. In one implementation, a sweep tool is generated through a sweeping operation of the sweeping profile along the corresponding sub-path, using a shape
25 manager call.

In block **416**, weld bead modeling function **114** determines whether the path is open. If the path is determined to be open, weld bead modeling function **114** correspondingly trims the sweep tools using shape manager calls, with their associated blanks B, and then initializes the trimmed sweeping tools as intermittent
5 fillet weld bead instances, blocks **418-420**.

Note that all operations within computing environment **100**, in substance are performed on data representations **122** of the faces, edges, vertices, blanks, paths, and tools. For ease of understanding, further description may not be burdened with the repeated clarification. However, the description should be so read, unless the
10 context clearly indicates otherwise.

Figure 5 illustrates the sub-path generation and naming operations of **Fig. 4** in further details, in accordance with one embodiment. As illustrated, weld bead modeling function **114** gets the named path P, block **502**, and determines an invariant weld generation direction, block **504**. In various implementations, the
15 determination includes the identification of a Global Start Vertex (GS) and a Global End Vertex (GE). Then, in block **506**, weld bead modeling function **114** sub-divides path P into ordered sub-paths. In various implementations, path P is sub-divided into equal length segments (edges with vertices), placed at distance d from each other. In various embodiments, the sub-division is effectuated by calling a curve
20 splitting function of the shape manager.

Then, weld bead modeling function **114** performs blocks **512-516** for each sub-path. More specifically, at block **512**, a sub-path is selected. Then, the edges and vertices of the selected sub-path are named, blocks **514-516**.

Figure 6 illustrates the invariant weld generation direction determination operation of **Fig. 5** in further details, in accordance with one embodiment. The embodiment assumes the following:

- Intermittent fillet welds are generated along Face-Sets (namely FS1 and FS2) that either belongs to the same component or two different components.
- All faces in a given Face-Set (e.g. FS1) are unique and belong to the same component. A face cannot belong to both face-sets.
- The path, P, is named such that each of its edges is uniquely named. All vertices of the named path P are assumed to be tagged uniquely from '1' through 'n'.
- Intermittent Fillet Weld Instances are of equal length placed along a continuous path and are equidistant from each other.
- The path is a single, non-degenerate, continuous and un-branched entity. However, the path may be open or closed.
- User defined pick point is provided by the user during selection of input face-sets FS1 and FS2.

Further, the "attributes" referred herein may have copy, split and merge behaviors, which can be specified. Attribute propagation and management services are available from the earlier identified shape manager or its equivalent. In alternate embodiments, this need may be addressed by any attribute or callback notification method that provides notification of model changes.

For the embodiment, to establish the invariant path direction, weld bead modeling function 114 establishes the global start (GS) and end (GE) vertices for the named path. As will be readily apparent from the descriptions to follow, GS and GE play an important part in generating consistent names for the sub-paths. The global

start vertex GS identifies the logical start of the path P and the global end vertex GE identifies the logical end. GS and GE are associated with unique integers known as the start-index (start vertex name, i.e., unique integer value at the start of P) and end-index (end vertex name, i.e., unique integer value at the end of P). These
5 names are termed as an index because they are used to identify GS and GE, which signify the path's direction along which the intermittent fillet weld will be generated. Thus, the start and end index together with the topology of path P are used to facilitate the establishment of order, i.e. unique direction in an otherwise unordered set of vertices of the path, P. This direction is invariant over successive re-computes
10 of the model.

To facilitate enforcement of the invariant direction, the start-index of the Global Start Vertex is cached, and made persistent. Over successive re-computes of the model, the GS vertex is identified using the cached start-index. As a result, the Global Start Vertex and Global End Vertex may be set to match the same
15 vertices over different computes of the model. In turn, that characteristic serves to maintain an invariant weld bead generation direction, as well as guarantee that the names for the sub-paths, and eventually the weld instances will be the same.

Referring now to **Fig. 6**, during creation of the sub-paths, weld bead modeling function **114** first determines whether path P is open or closed, block **602**. GS and
20 GE are then identified based on the path type.

If path P is determined to be open, path P, by definition, has two open ends. Accordingly, weld bead modeling function **114** first locates the two open ends, block **604**. Then, weld bead modeling function **114** determines which one of the two open ends is closest to the user's pick pint, block **606** (see also **Fig. 8a**). In various
25 implementations, weld bead modeling function **114** selects the vertex that is closest

to the user's pick point as GS (the user's pick point is an actual point on the face where the user clicked first to select the faces to weld). Additionally, weld bead modeling function 114 selects the other open end as GE.

5 In some cases, the two open ends could be at equal distances to the user-selected pick point. In various implementations, weld bead modeling function 114 arbitrarily chooses one of the points as GS.

If path P is determined to be closed, weld bead modeling function 114 proceeds to determine whether path P is a single or multiple segment path, block 610. A closed single segment path has only one vertex (see also Fig. 8b). In 10 various implementations, weld bead modeling function 114 initializes that single vertex as both GS and GE. For closed multi-segmented paths (see also Fig. 8c), weld bead modeling function 114 determines the vertex whose name value is the lowest and the next lowest. In various implementations, the vertex names are integers. Weld bead modeling function 114 selects the vertex with the lowest value 15 as GS, block 614, and the vertex with the next lowest value as GE, block 616.

Regardless of, whether path P is open, or a closed single/multi segment, after selection, the start-index of GS is cached/stored. As will be described in more detail below, the cached/stored GS facilitates establishment of the invariant weld bead generation direction, and in turn, facilitates the persistent and proper naming of the 20 sub-paths during re-computes of the model (due to e.g. user editing and modification to the weld parameters).

As will be described in more detail below, during edits, weld bead modeling function 114 retrieves the cached value of the start-index. If the path is open, weld bead modeling function 114 finds the vertex in the path whose name value matches 25 with the start-index. The matched vertex is initialized as GS. The other open end is

initialized as GE. If the path is closed, and has one segment, weld bead modeling function 114 initializes the only vertex as GS and GE. If the path is closed and has multiple segments, weld bead modeling function 114 uses the start-index to find the GS. Weld bead modeling function 114 then obtains the two neighboring edges
5 around GS and collects all the candidate vertices except the vertex whose name is GS. From the two candidate vertices, weld bead modeling function 114 finds the vertex that has the lowest integer value and initializes it as GE.

Figure 7a illustrates the sub-division operation of Fig. 5 in further details, in accordance with one embodiment. For the embodiment, given a multi-edge
10 continuous path P, the edge that contains the GS vertex is used to identify the first edge for subdivision. Accordingly, weld bead modeling function 114 first selects the edge containing GS, block 702, and sub-divides the selected edge, block 704. In various implementations, as described earlier, the sub-division is performed by weld bead modeling function 114 invoking a curve splitting function. In various
15 implementations, the curve splitting function is available from the shape manager.

Then, weld bead modeling function 114 selects the next connected edge, in accordance with the invariant weld generation direction, block 706, and subdivides that edge, block 708. The process is repeated until all edges have been subdivided. (See also Fig. 9a-9b)

20 In various implementations, for a multi-edge path where the edges are numbered 1 – n, the GS Vertex is considered to be attached to edge 1. Thus, the above process may be re-stated as having weld bead modeling function 114 first selects and sub-divides edge 1, then moves to edge 2, and so forth, until edge n is selected and sub-divided.

Accordingly, the edge subdivision process results in a number of sub-paths. These sub-paths along with the sweeping profiles will be used to generate the intermittent fillet weld instances.

Figure 7b illustrates the naming operations of **Fig. 5** in further detail, in accordance with one embodiment. In various embodiments, a persistent table referred to as the name table, which contains non-duplicate rows and two columns (Column 1, and Column 2) is employed. The table has certain abilities. One such ability is known as Insertion. Given a n-tuple of "access" data D in Column 1, Left Hand Side (LHS), the table function can generate a unique Right Hand Side (RHS) integer value. In the Insertion function, given "access" data D,

- If a match exists for D in any row in Column 1, it retrieves and returns the corresponding Right Hand Side (RHS) value in Column 2 for the same row.
- If a match does not exist for D in any row in Column 1, it inserts the given data in Column 1 (LHS) into a new row at the end and generates a unique integer in Column 2 for the same row known as the RHS value.

An example of the table is shown below.

A name $N_{e/v}$, for the edge or the vertex of a sub-path is generated by constructing the LHS value as a 3-tuple using the following:

- N_p : Name of the progenitor edge,
- S_i : Split-index.
- VF: Vertex-flag is equal to -1 when we are naming an edge. For naming a vertex, Vertex Flag is equal to 0 for a start vertex and 1 for the end vertex of each sub-path.

$$\{N_p, S_i, VF\} \dots = N_{e/v} \dots \text{Eq. 1}$$

As shown in Eq 1, the name $N_{e/v}$ for an edge or vertex is deduced by the 3-tuple on the LHS. The RHS value is the resulting name for the edge or vertex.

When a new name needs to be generated, weld bead modeling function 114 inserts the LHS value into the name table. For the LHS value, the name table
5 returns a RHS value. The next time the weld bead is re-computed, if the LHS value matches, the table function returns the existing names. In various implementations, if the user changes input data such that it results in fewer sub-paths, the unused sub-path names are not deleted. Instead they are left in the table for later reuse. However, if the weld bead is completely destroyed, the table is destroyed.

10 The ordered sub-paths are processed sequentially. Each edge is named first followed by its vertices. The process continues for all the remaining edges in the sub-paths.

Referring now to **Fig. 7b**, weld bead modeling function 114 first selects a sub-path, including its edge and vertices, blocks 712-714. Then, for each edge and
15 vertex on the sub-path, weld bead modeling function 114 generates a name for it by constructing a 3-tuple on the LHS and then using the Insertion function in the name table to get a unique integer on the RHS, and assigns to the edge/vertex, blocks 718-738.

For the LHS value, weld bead modeling function 114 first obtains the name of
20 the progenitor edge N_p , block 718. In various implementations, N_p is deduced through the attributes on the split edge. More specifically, for these implementations, every edge of the path P has an attribute (known as EntityNameAttribute), which contains the unique edge name, N_e .

When an edge of path P is split into multiple sub-paths, resulting in sub-path
25 edges, the original name of the edge is copied onto each edge of the sub-path by

virtue of the split behavior. This is useful in preserving the relationship between a sub-path's edge and its progenitor edge. From the sub-path's edge the EntityNameAttribute is obtained, and then from this attribute the name of the progenitor edge, N_e is obtained.

5 In various implementations, during the creation of the sub-paths, the curve splitting function also attaches a split-attribute to the edges of path P which contains information about the split index of the sub-path. For these implementations, weld bead modeling function **114** retrieves the split index S_i , from the split attribute on the edges of the sub-path, block **720**. The split index signifies the order in which the
10 segments were split.

 At block **722**, weld bead modeling function **114** determines whether the topological items to be named is a vertex. If not, weld bead modeling function **114** sets the vertex flag to -1 (for an edge), block **724**. Then, weld bead modeling function **114** constructs the LHS value, block **732**. In various implementations, the
15 construct is performed as shown in Equation 1. Further, weld bead modeling function **114** performs insertion into the name table, block **734**, resulting in a RHS name being generated by the table function, block **736**. The unique integer resulting from the LHS value is then assigned to the edge, block **738**.

 Then, weld bead modeling function **114** collects and processes all the
20 vertices of the edge. At first, weld bead modeling function **114** identifies whether the vertex corresponds to a start or end vertex, block **726**. In various implementations, this is deduced based on GS and GE. As before, the LHS value is constructed as shown in Equation 1, and the split index is collected from the edge that uses the vertex.

In blocks **728-730**, weld bead modeling function **114** sets the Vertex Flag for a Start vertex to 0, and End Vertex to 1. The LHS value is inserted into the name table to get a RHS value as before, blocks **732-736**. The RHS value is assigned to the unnamed vertex, block **738**.

5 **Figures 10a-10b** illustrate an example of sub-path division and naming. The path P has 3 edges E1, E2, E3. E1 has an edge name of $N_{e1}=5$, E2's edge name is $N_{e2}=6$, and E3's edge name to be $N_{e3}=7$. The vertices of E1 are named as $N_{v1}=1$, $N_{v2}=2$, vertices of E2 as $N_{v2}=2$ and $N_{v3}=3$ and vertices of E3 as $N_{v3}=3$ and $N_{v4}=4$. GS and GE are also shown in Figure 10b.

10 After subdivision, the three path segments in **Figure 10a** are subdivided into eight segments as shown in **Figure 10b**.

The following table shows how names are generated for the sub-paths of E1.

Object	Entity Type	N _p	LHS value		RHS value	
			S _i	VF	N _{e/v}	
E1,1	Edge	5	1	-1	8	
V1,1,S	Start Vertex	5	1	0	9	
V1,1,E	End Vertex	5	1	1	10	
E1,2	Edge	5	2	-1	11	
V1,2,S	Start Vertex	5	2	0	12	
V1,2,E	End Vertex	5	2	1	13	
E1,3	Edge	5	3	-1	14	
V1,3,S	Start Vertex	5	3	0	15	
V1,3,E	End Vertex	5	3	1	16	

At first E1,1 is processed. Its 3-tuple is {5,1,-1} which results in a RHS value of 8. Next vertices, V1,1,S and V1,1,E are processed. For V1,1,S the 3-tuple is {5,1,0}. Note that the vertex flag is set to 0 since it corresponds to a start vertex.

5 For, V1,1,E the 3-tuple is {5,1,1} which results in a edge name of 10. Since it corresponds to an end vertex its vertex flag is set to 1. Edge E1,2 has a 3-tuple of {5,2,-1}. Note that the Vertex Flag for this edge is -1 since it is not a vertex. By inserting this into the name table, an edge name of 11 is obtained. Since both vertices of Edge 1,2 are not named, the 3-tuples {5,2,0} and {5,2,1} result in names
10 12 and 13 respectively for the vertices V1,2,S and V1,2,E. This process continues until all the edges i.e. E1,3, E2,1, E2,2, E3,1, E3,2, E3,3, and their vertices are named.

Refer now to **Fig. 11**, as illustrated, in certain cases, the sub-path can span more than one vertex on path P. For the illustrated situation, the sub-path gets its progenitor edges in-part from E1 and in-part from E2. For example the vertex with name $N_{v2}=2$ on the path P, before split, remains in the sub-path generated after split.

- 5 For the sub-path shown after split, the 3-tuple for the start vertex V1,S is {4,1,0} which results in a new name of 6. The 3-tuple for the end vertex V1,E is {5,1,1} which results in a new name of 7. Segments E11 and E21's 3-tuples correspond to {4,1,-1} and {5,1,-1} which correspond to edge names of 8 and 9.

Persistent naming methods should be consistent and exhibit robust behavior.

- 10 Since a model can go through a number of geometry and topology changes due to user edits, the method preferably should ensure that the names generated are unique and invariant. This will ensure that any downstream features depending on the topological entity will update successfully.

Figures 12a-12b illustrate two sub-path views of an editing example. **Fig.**

- 15 **12a** shows a path P having been sub-divided into 3 sub-paths, for the eventual generation of 3 intermittent fillet weld instances. The edges and vertices of the 3 sub-paths are named as described earlier.

- The example assumes the weld parameters were edited by e.g. a user, changing the number of intermittent weld instances desired from 3 to 4. The names
20 of sub-paths, including their edges and vertices, are re-computed in accordance with the earlier described method, and the results are shown in **Figure 12b**.

- As illustrated, by virtue of the invariant weld generation direction, and naming in accordance with the direction, the sub-path segments E1,1 and E1,2 and E1,3, and their corresponding vertices V(1,1,S), V(1,1,E), V(1,2,S), V(1,2,E), V(1,3,S),
25 V(1,3,E) in **Fig. 12a** and in **Fig. 12b** get the same names. Sub-path E1,4 and its two

vertices V(1,4,S) and V(1,4,E) in **Fig. 12b**, get new names. Edge E1,4, gets the name, 13, and vertices: V (1,4,S) and V(1,4,E) get the names 14 and 15 respectively.

5 The name table used to generate the names for the vertices and edges for the example shown in **Fig. 12b** is shown below.

Object	Entity Type	LHS value			RHS value	
		N _p	S _i	VF	N _{e/v}	
E1,1	Edge	3	1	-1	4	
V1,1,S	Start Vertex	3	1	0	5	
V1,1,E	End Vertex	3	1	1	6	
E1,2	Edge	3	2	-1	7	
V1,2,S	Start Vertex	3	2	0	8	
V1,2,E	End Vertex	3	2	1	9	
E1,3	Edge	3	3	-1	10	
V1,3,S	Start Vertex	3	3	0	11	
V1,3,E	End Vertex	3	3	1	12	
E1,4	Edge	3	4	-1	13	
V1,4,S	Start Vertex	3	4	0	14	
V1,4,E	End Vertex	3	4	1	15	

Note that the 3-tuple for edges E1,1, E1,2, E1,3 and vertices V(1,1,S), V(1,1,E), V(1,2,S), V(1,2,E), V(1,3,S), V(1,3,E) are: {3,1,-1}, {3,2,-1}, {3,3,-1}, for edges, {3,1,0}, {3,1,1}, {3,2,0}, {3,2,1}, {3,3,0}, {3,3,1} for vertices respectively.

These names are the same before and after edit. Hence, the naming table

- 5 invariantly returns the same RHS values for these sets of 3-tuples, i.e. 4, 7, 10, for edges and 5, 6, 8, 9, 11, 12 for vertices respectively. Sub-path segment E1,4 shown in **Fig. 12b** is a new segment due to the editing process. The edge's 3-tuple {3,4,-1} results in a new name of 13. The vertices' 3-tuples V(1,4,S) and V(1,4,E) will result in new names of 14 and 15 being returned. Thus the names are unique and
- 10 invariant after successive compute operations.

- Referring back to **Fig. 4**, as earlier described, after sub-paths are generated, and their edges and vertices are named, blocks **408-410**, a sweeping profile is created and named, block **412**, and the sweeping profile is employed to generate the sweeping tools, block **414**. In turn, the sweeping tools are initialized as the
- 15 intermittent weld bead instances (with or without having been trimmed using body B), blocks **418-420**.

- Fig. 13a** illustrates an example triangular sweeping profile, in accordance with one embodiment. Using the example profile, sweeping along one of the sub-path of path P, results in an intermittent fillet weld instance of **Fig. 13b**. Repeating the
- 20 process for all other sub-paths of path P results in the generation of the intermittent fillet weld bead of **Fig. 13c**, assuming 3 sub-paths for the example, and path P is an open path. However, in another example where path P is a multi-segment closed path with 11 sub-paths, repeating the process for all other sub-paths of path P results in the generation of the intermittent fillet weld bead of **Fig. 13d**.

As illustrated by **Fig. 13e**, the resulting intermittent fillet weld bead may have dependent features. For the example of **Fig. 13e**, the intermittent fillet weld bead has a machining feature (e.g. a hole) passing through instance no. 2, and a workplane at one of the faces of instance no. 2.

5 As described earlier with references to **Fig. 12a-12b**, names of the topological entities of the sub-paths are persistently maintained across re-computations of the intermittent weld bead models, due to e.g. editing by a user. The editing may be of a direct type (i.e. editing the weld bead itself) or an indirect type (i.e. editing an upstream feature to which the weld bead depends).

10 **Figures 14a-14b** illustrate two external views of two examples of persistent naming across re-computations, due to direct editing. More specifically, **Fig. 14a** illustrates an example of persistent naming across re-computations due to direct editing of the intermittent fillet weld bead of **Fig. 13c**. In this example, the length of the instance and the pitch of the weld bead have been changed. Resultantly, more
15 number of fillet weld instances are produced. The unique and invariant names for the sub-paths are generated as earlier described, referencing **Fig. 12a-12b**.

Fig. 14b illustrates another example of persistent naming across re-computations due to direct editing of the intermittent fillet weld bead of **Fig. 13e**. In this example, the instance length and distance between the instances have been
20 changed. Resultantly, more number of fillet weld instances are produced. However, the dependent features are still attached to instance no.2 after the edit operation. The weld bead is guaranteed to be recomputed successfully with the same names on the topological entities of the sub-paths, as long as the input data is valid, i.e. a valid intersection can be computed from the intersection of FS1 and FS2 to generate

a path P. The unique and invariant names for the sub-paths are generated as earlier described, referencing **Fig. 12a-12b**.

Thus, it can be seen from the above descriptions, embodiments of a novel method to name sub-paths, including their edges and vertices, of a continuous path of an intermittent fillet weld bead, having particular application to the generation of intermittent weld bead, have been described. While the novel method has been described in terms of the foregoing embodiments, those skilled in the art will recognize that the method is not limited to the embodiments described. The method may be practiced with modifications and alterations within the spirit and scope of the appended claims.

Accordingly, the description is to be regarded as illustrative instead of restrictive.